



Probability in Machine Learning



Three Axioms of Probability

- Given an Event E in a sample space S , $S = \bigcup_{i=1}^N E_i$
- First axiom
 - $P(E) \in \mathbb{R}, 0 \leq P(E) \leq 1$
- Second axiom
 - $P(S) = 1$
- Third axiom
 - Additivity, any countable sequence of mutually exclusive events E_i
 - $P(\bigcup_{i=1}^n E_i) = P(E_1) + P(E_2) + \cdots + P(E_n) = \sum_{i=1}^n P(E_i)$



Random Variables

- A random variable is a variable whose values are numerical outcomes of a random phenomenon.

- Discrete variables and Probability Mass Function (PMF)

$$\sum_x p_X(x) = 1$$

- Continuous Variables and Probability Density Function (PDF)

$$\Pr[a \leq X \leq b] = \int_a^b f_X(x) dx$$



Expected Value (Expectation)

- Expectation of a random variable X:

$$E[X] = \sum_{i=1}^k x_i p_i = x_1 p_1 + x_2 p_2 + \cdots + x_k p_k.$$

- Expected value of rolling one dice?



$$E[X] = 1 \cdot \frac{1}{6} + 2 \cdot \frac{1}{6} + 3 \cdot \frac{1}{6} + 4 \cdot \frac{1}{6} + 5 \cdot \frac{1}{6} + 6 \cdot \frac{1}{6} = 3.5.$$

https://en.wikipedia.org/wiki/Expected_value



Expected Value of Playing Roulette

- Bet \$1 on single number (0 ~ 36), and get \$35 payoff if you win. What's the expected value?

$$E[\text{Gain from \$1 bet}] = -1 \times \frac{36}{37} + 35 \times \frac{1}{37} = \frac{-1}{37}$$



Variance

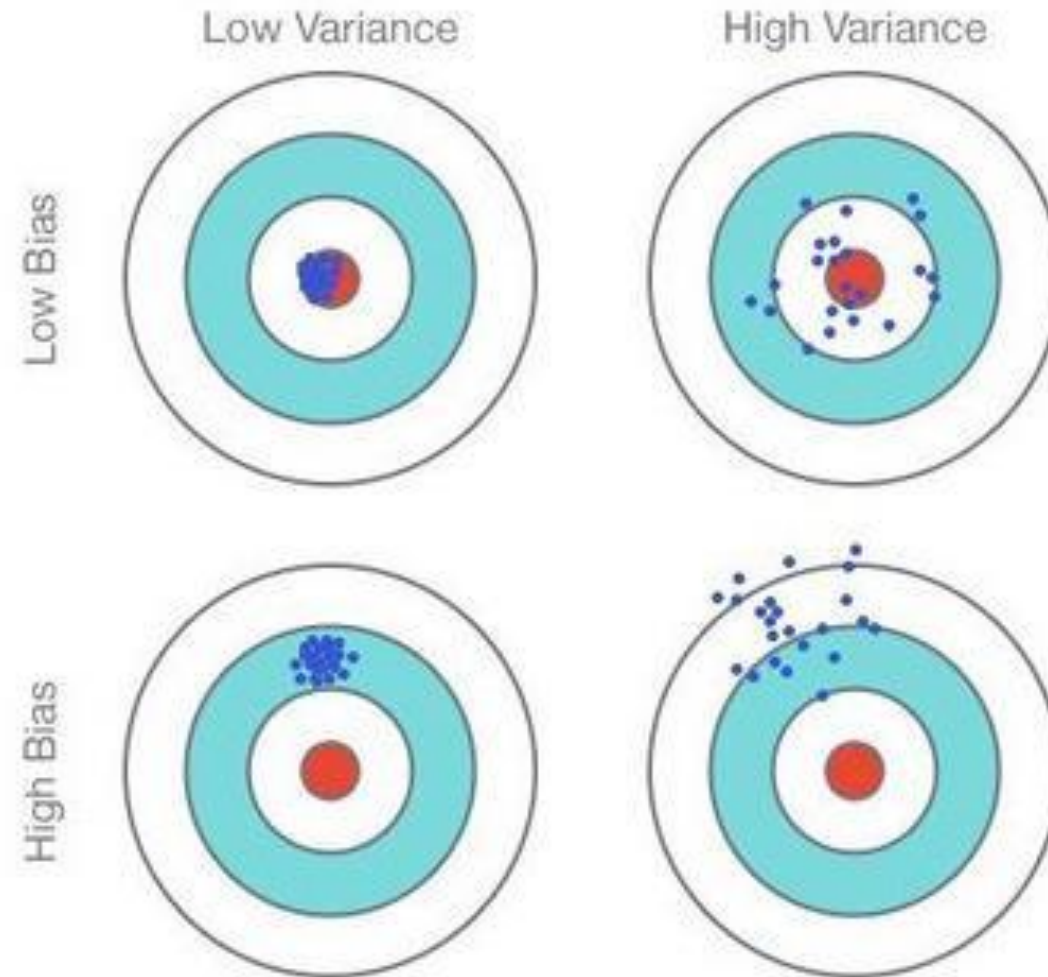
- The variance of a random variable \mathbf{X} is the expected value of the squared deviation from the mean of \mathbf{X}

$$\text{Var}(\mathbf{X}) = E[(\mathbf{X} - \mu)^2]$$

$$\begin{aligned}\text{Var}(X) &= E[(X - E[X])^2] \\ &= E[X^2 - 2XE[X] + E[X]^2] \\ &= E[X^2] - 2E[X]E[X] + E[X]^2 \\ &= E[X^2] - E[X]^2\end{aligned}$$



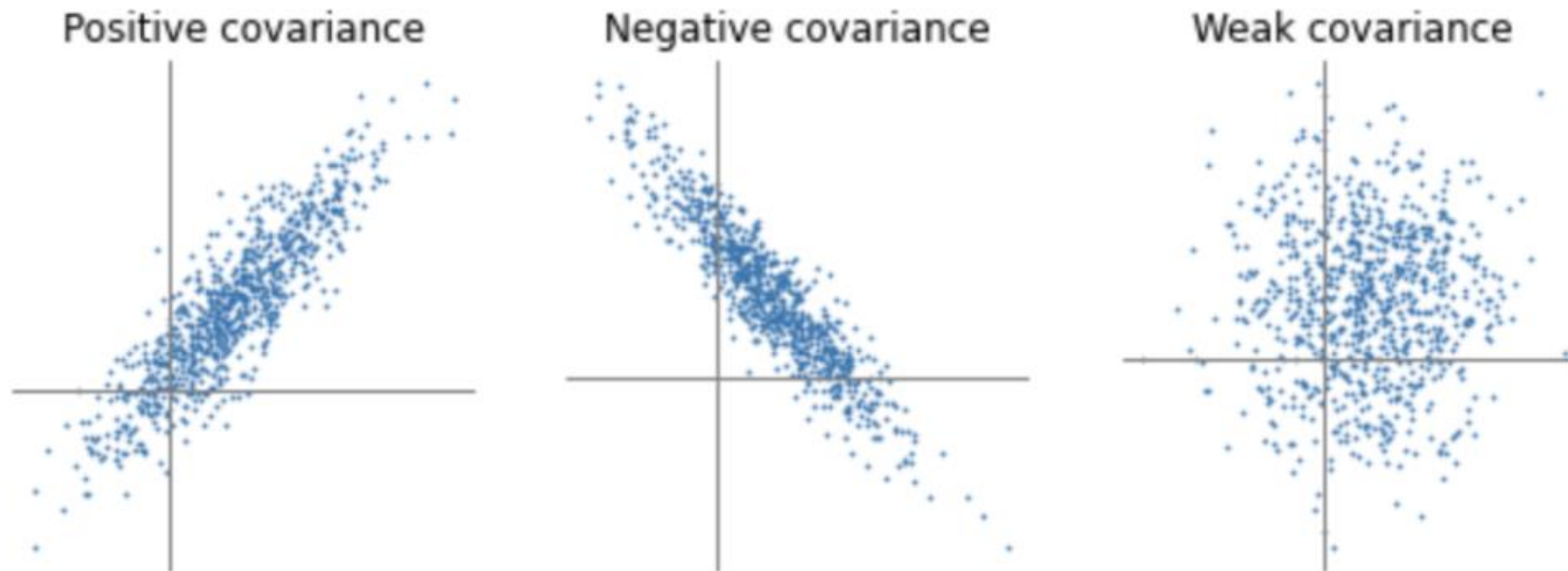
Bias and Variance



Covariance

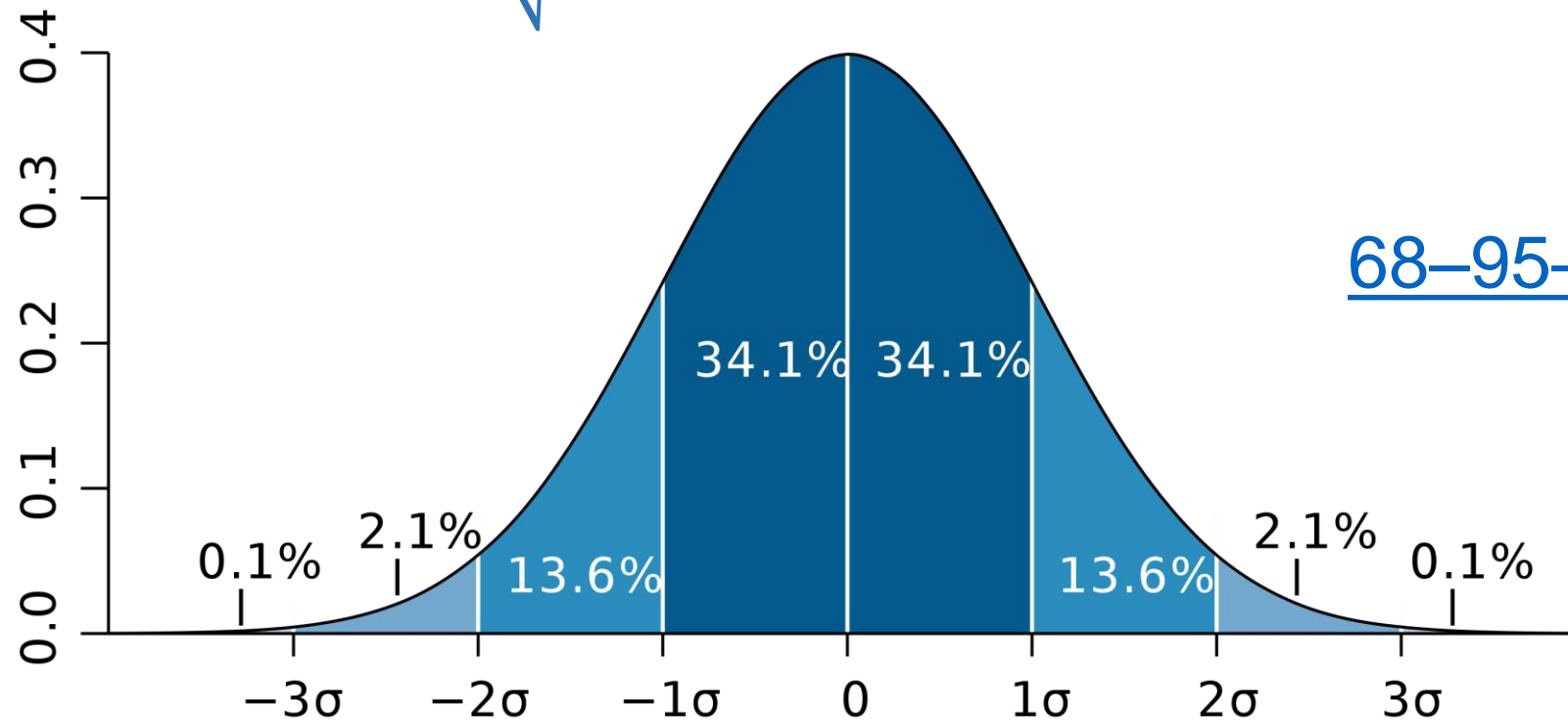
- Covariance is a measure of the joint variability of two random variables.

$$\text{Cov}(X, Y) = E[X - E[X]]E[Y - E[Y]] = E[XY] - E[X]E[Y]$$



Standard Deviation

$$\sigma = \sqrt{\frac{1}{N} \sum_{i=1}^N (x_i - \mu)^2} = \sqrt{\text{Var}(X)}$$



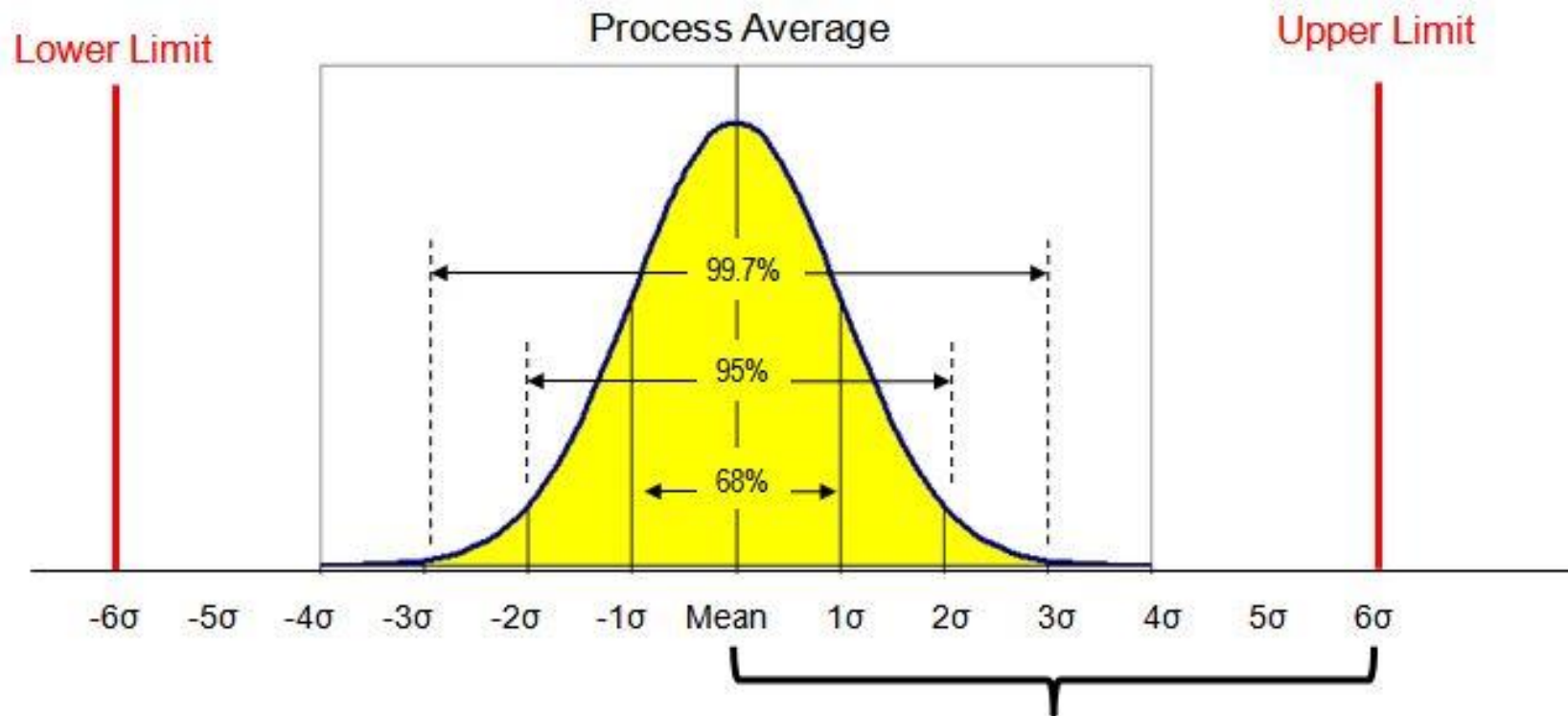
68–95–99.7 rule



6 Sigma



- A product has 99.99966% chance to be free of defects

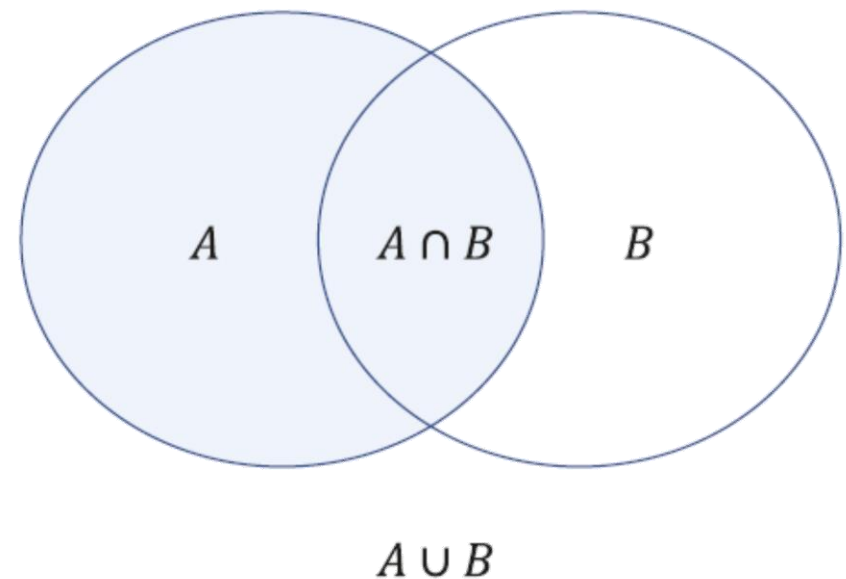


Union, Intersection, and Conditional Probability

- $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
- $P(A \cap B)$ is simplified as $P(AB)$
- Conditional Probability $P(A|B)$, the probability of event A given B has occurred

$$- P(A|B) = P\left(\frac{AB}{B}\right)$$

$$- P(AB) = P(A|B)P(B) = P(B|A)P(A)$$



Chain Rule of Probability

- The joint probability can be expressed as chain rule

$$P(A_1 A_2 A_3 \dots A_n) = P(\cancel{A_1}) P(A_2 / A_1) P(A_3 / A_1 A_2) \dots P(A_n / A_1 A_2 \dots A_{(n-1)})$$

$$\frac{P(\cancel{A_1} A_2)}{P(\cancel{A_1})}$$

$$\frac{P(A_1 A_2 A_3)}{P(\cancel{A_1} A_2)}$$



Mutually Exclusive

- $P(AB) = 0$
- $P(A \cup B) = P(A) + P(B)$



Independence of Events

- Two events A and B are said to be independent if the probability of their intersection is equal to the product of their individual probabilities

$$P(AB) = P(A)P(B)$$

$$P(A|B) = P(A)$$



Bayes Rule

Training Data

Likelihood

Prior

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Class
(Cat / Dog)

features
(Pixels of an image)

Evidence

Proof:

Remember $P(A|B) = P\left(\frac{AB}{B}\right)$

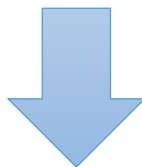
So $P(AB) = P(A|B)P(B) = P(B|A)P(A)$

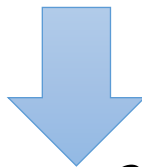
Then Bayes $P(A|B) = P(B|A)P(A)/P(B)$



Naïve Bayes Classifier

$$p(C_k \mid \mathbf{x}) = \frac{p(C_k) p(\mathbf{x} \mid C_k)}{\cancel{p(\mathbf{x})}}$$

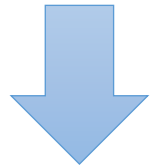

$$p(C_k \mid x_1, \dots, x_n)$$


$$\begin{aligned} p(C_k, x_1, \dots, x_n) &= p(x_1, \dots, x_n, C_k) \\ &= p(x_1 \mid x_2, \dots, x_n, C_k) p(x_2, \dots, x_n, C_k) \\ &= p(x_1 \mid x_2, \dots, x_n, C_k) p(x_2 \mid x_3, \dots, x_n, C_k) p(x_3, \dots, x_n, C_k) \\ &= \dots \\ &= p(x_1 \mid x_2, \dots, x_n, C_k) p(x_2 \mid x_3, \dots, x_n, C_k) \cdots p(x_{n-1} \mid x_n, C_k) p(x_n \mid C_k) p(C_k) \end{aligned}$$



Naïve = Assume All Features Independent

$$p(x_i \mid x_{i+1}, \dots, x_n, C_k) = p(x_i \mid C_k)$$

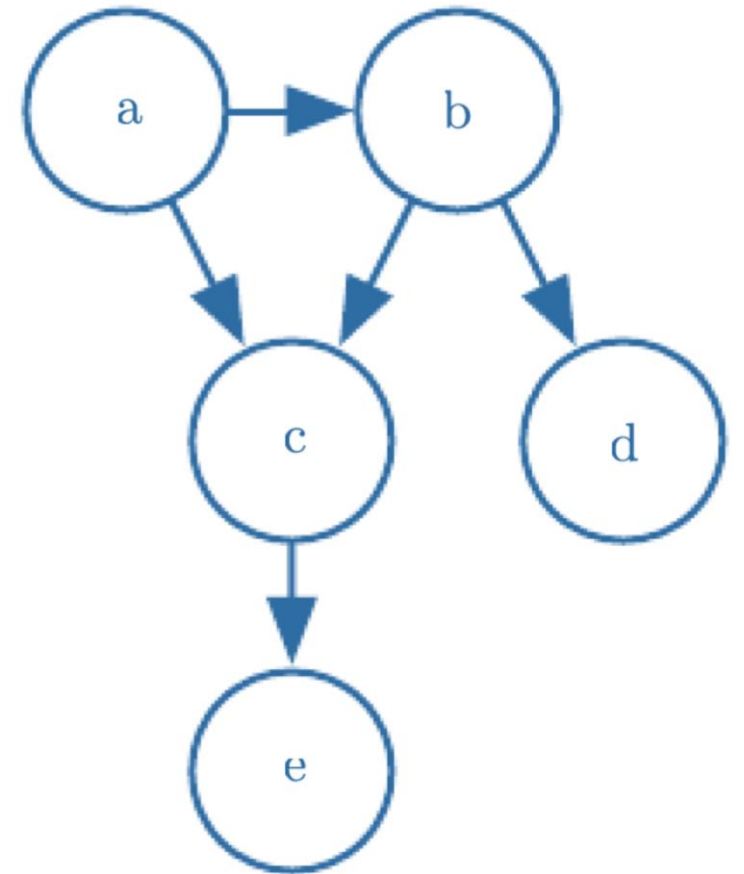


$$\begin{aligned} p(C_k \mid x_1, \dots, x_n) &\propto p(C_k, x_1, \dots, x_n) \\ &= p(C_k) p(x_1 \mid C_k) p(x_2 \mid C_k) p(x_3 \mid C_k) \cdots \\ &= p(C_k) \prod_{i=1}^n p(x_i \mid C_k), \end{aligned}$$



Graphical Model

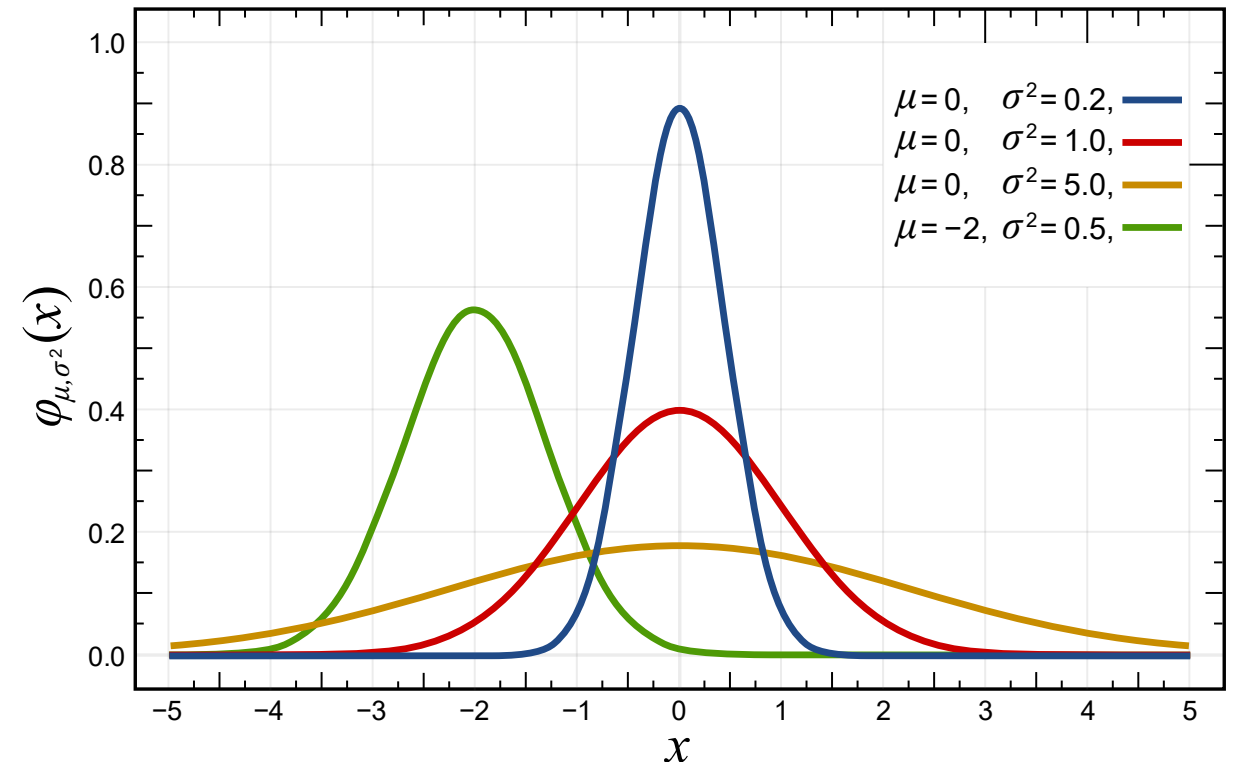
$$p(a, b, c, d, e) = p(a)p(b|a)p(c|a, b)p(d|b)p(e|c)$$



Normal (Gaussian) Distribution

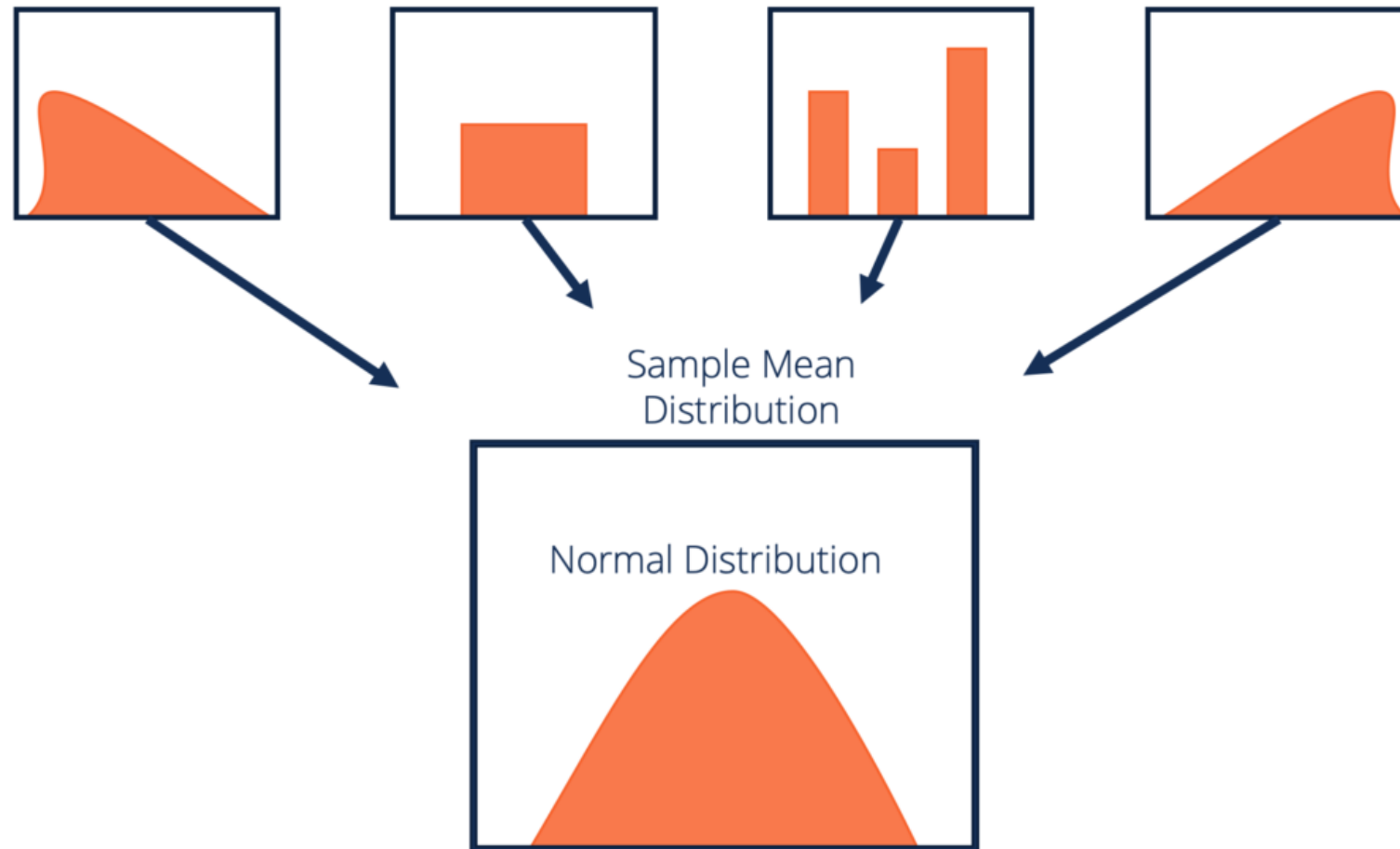
- A type of continuous probability distribution for a real-valued random variable.
- One of the most important distributions

$$f(x \mid \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



Central Limit Theory

- Averages of samples of observations of random variables independently drawn from independent distributions converge to the normal distribution



Bernoulli Distribution

- Definition

$$\Pr(X = 1) = p = 1 - \Pr(X = 0) = 1 - q.$$

- PMF

$$f(k; p) = \begin{cases} p & \text{if } k = 1, \\ q = 1 - p & \text{if } k = 0. \end{cases}$$

- $E[X] = p$

- $\text{Var}(X) = pq$



<https://acegif.com/flipping-coin-gifs/>



Information Theory

- Self-information:

$$I(x) = -\log P(x)$$

$$\log \frac{1}{P(x)} = -\log P(x)$$

- Shannon Entropy:

$$H = -\sum_i p_i \log_2 p_i$$



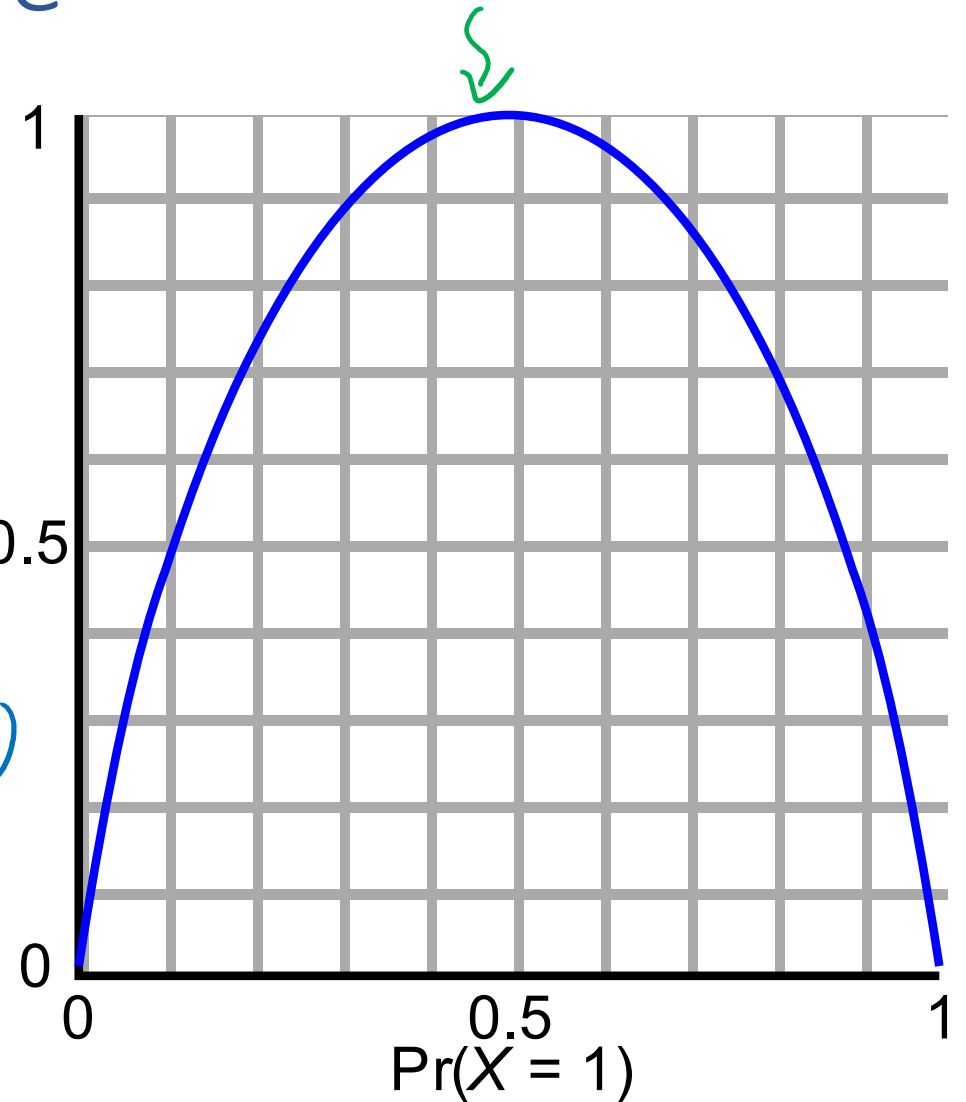
Entropy of Bernoulli Variable

- $H(x) = E[I(x)] = -E[\log P(x)]$

$$H(x) = -0.5 \times \log_2 \frac{1}{2} - 0.5 \times \log_2 \frac{1}{2} \quad \text{H(X)} \quad \text{= 1}$$

$$H(X) = -1 \times \log_2 1 - 0 \times \log_2 0 \quad \text{Pr(X=1)} \quad \text{0}$$

https://en.wikipedia.org/wiki/Information_theory



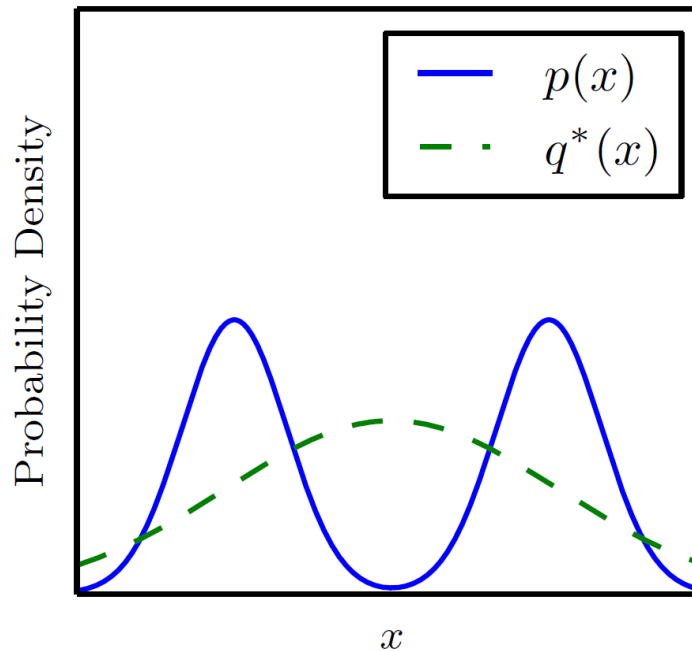
Kullback-Leibler (KL) Divergence

- $D_{KL}(p||q) = E[\log P(X) - \log Q(X)] = E \left[\log \frac{P(x)}{Q(x)} \right]$

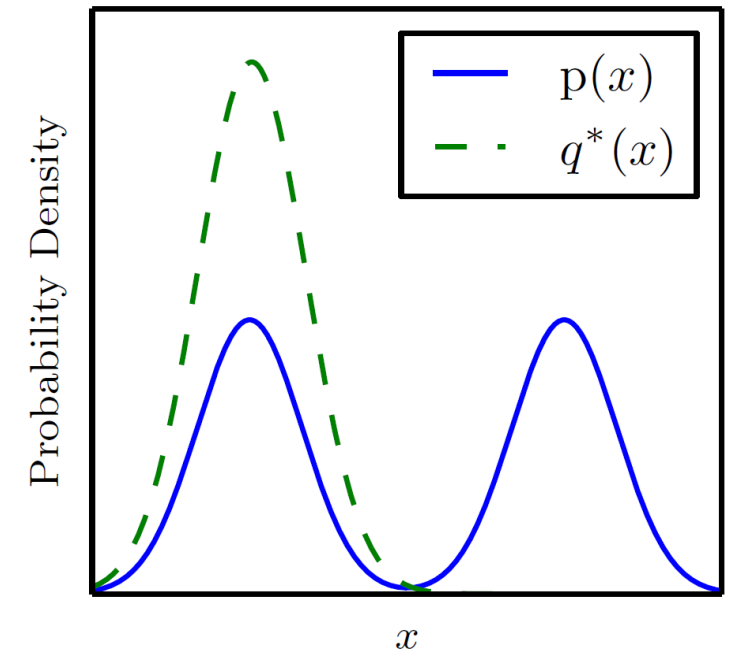
KL Divergence is
Asymmetric!

$$D_{KL}(p||q) \neq D_{KL}(q||p)$$

$$q^* = \operatorname{argmin}_q D_{KL}(p||q)$$



$$q^* = \operatorname{argmin}_q D_{KL}(q||p)$$



Key Takeaways

- **Expected value** (expectation) is **mean** (weighted average) of a random variable
- Event A and B are independent if $P(AB) = P(A)P(B)$
- Event A and B are mutually exclusive if $P(AB) = 0$
- Central limit theorem tells us that **Normal distribution** is the one, if the data probability distribution is unknown
- Entropy is expected value of self information $-E[\log P(x)]$
- **KL divergence** can measure the difference of two probability distributions and is asymmetric

